



## Protocol Description

### WRF06-RS485-Modbus

## Index of Changes

Rvision	Date	Description
K	21.05.2014	Description for BELIMO 6-way valve added (from firmware 2.10 and configuration software 2.5 or higher)

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## 1 WRF06-RS485-Modbus

The present document describes the serial interface of the room operating panel WRF006-RS485-MODBUS. The MODBUS protocol developed by the company Modicon is an open protocol for the communication of various intelligent devices on Master-Slave base.

For further information and definitions on the topic MODBUS, please see [www.modbus.org](http://www.modbus.org).

## 2 Device Description

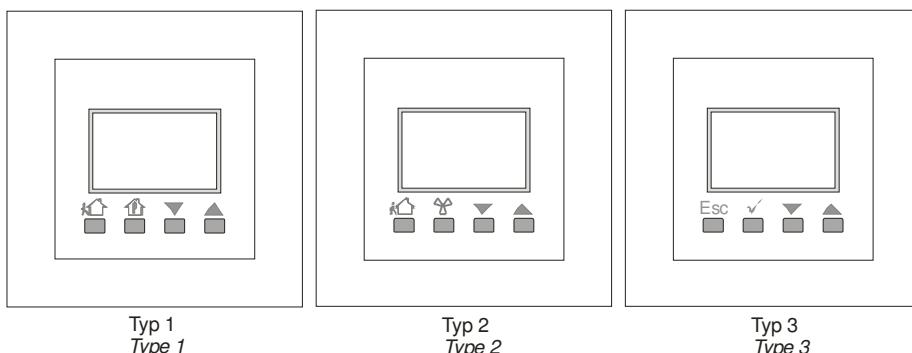
### 2.1 Device types

The WRF06-RS485-Modbus could be delivered in different types.

- Devices without temperature controller
  - Type 2V      Analogue output 1: temperature, Analogue output 2: set point
  - Type4DI      4 digital input
  - Type2VPS     Analogue output 1: room occupancy, Analogue output 2: set point
  - TypeVSS      Analogue output 1: set point 2, Analogue output 2: set point 1
  - Type VNS     Analogue output 1: temperature, Analogue out 2: set point night temp
- Devices with temperature controller
  - Type AO2V    Analogue output 1: Heating, Analogue output 2: Cooling
  - Type DO2R    Digital output 1: Heating, Digital output 2: Cooling
  - Type DO2T    Digital output 1: Heating, Digital output 2: Cooling
  - Type OVR     Digital output 1: Heating, Analogue output 2: Cooling
  - Type OVT     Digital output 1: Heating, Analogue output 2: Cooling
  - Type AOV     Analogue output 2: Heating / cooling, Changeover-mode
  - Type AOFV    Analogue output 1: Fan speed,  
                  Analogue output 2: Heating / cooling, Changeover-mode
  - Type AOK     Analogue output 1: Heating, Analogue output 2: Cooling  
Kampmann 0-3V Off, 3-10 V On (0...100%)
  - Type 6WV    Analogue output 1: Fan speed,  
                  Analogue output 2: Cooling 2..4,7V / Heating 7,3..10V  
BELIMO 6-Way Valve

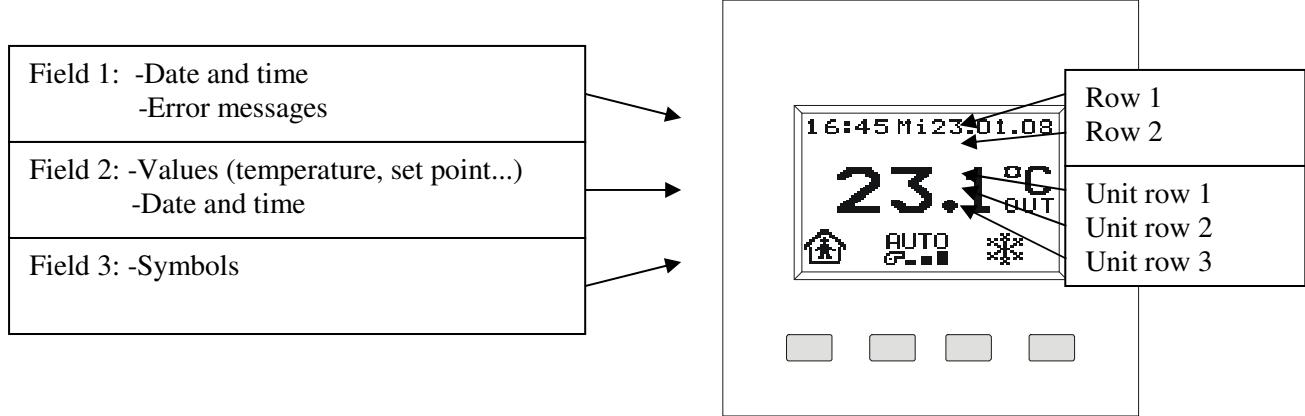
### 2.2 Display-printing

The display of WRF06-RS485-Modbus is in 3 types possible. Other printings are of request possible.



## 2.3 LCD- Display

The display is divided into 3 display areas: field 1 in the upper range, field 2 in the middle and field 3 in the bottom range.



The symbols displayed and their functions are as follows:

 Set point adjustment

 Error

 Heating

 Cooling

 Window "open"

 De point detector "active"

  Occupied (comfort) / Unoccupied (stand-by)

 Fan off

 Fan stage 1

 Fan stage 2

 Fan stage 3

 Fan off

 Fan stage 1

 Fan stage 2

 Fan stage 3

By means of the LCD-display different values can be displayed. As a standard, only the temperature is indicated. The values to be shown in the display can be set via the configuration 0x0000 – 0x000A. The following values can be indicated in the display:

- Temperature
  - Room temperature
  - 2 field programmable text rows in field 11
- 2 Set Points
  - Unit and display are field definable
  - Set point effective and offset
  - Adjustment via operating buttons possible
  - Per value 2 field parameterizable text rows in field 1

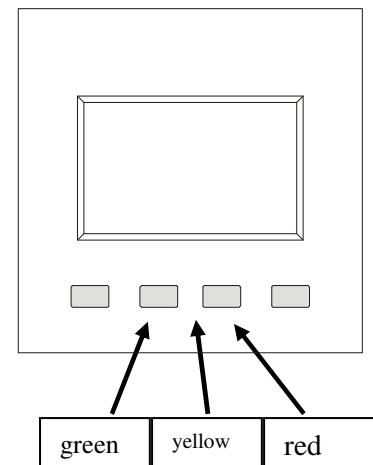
- 4 External Measuring Values
  - Unit and display are field definable
  - e.g. for outdoor temperature, pressure, percent value etc.
  - Per value 2 field parameterizable text rows in field 1
- 4 Alarm Messages
  - 2 external values e.g. for time, pressure etc.
  - 2 set points effective and offset
  - Per message 2 field parameterizable text rows in field 1

## 2.4 Lower Part of Device (base plate): LED Display

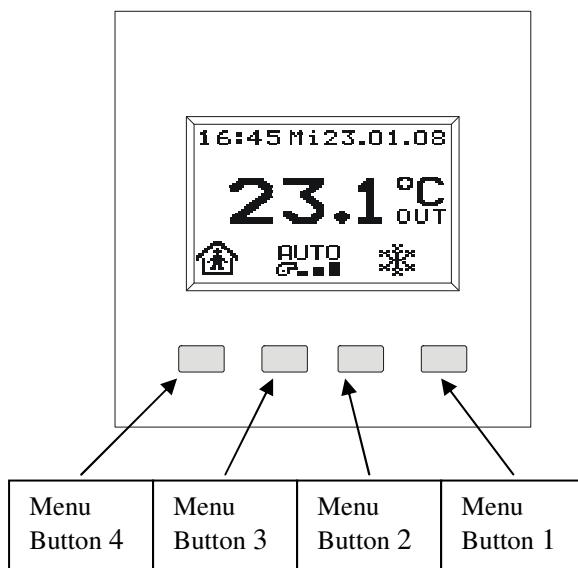
The room operating panel has 3 LEDs for the indication of different status for verifying device functions and bus communication.

- Green LED: Operating voltage
- Yellow LED: Flashes upon receipt of a flawless telegram which was addressed to the device.
- Red LED: Flashes upon receipt of a telegram, which was addressed to another device.
- Yellow + Red LED: Flashes upon receipt of a flawless telegram.

If telegrams are sent from the Master and no LEDs are flashing at the operating unit, the communication properties must be verified.



## 2.5 Definition Button Numeration



The respective function of the button can be set via the register 0x0006 – 0x0009.  
The following button functions are possible:

- Button pushed / not pushed e.g. for light, blinds
  - Output in output registers 257-258
  - Register 257 shows current status of buttons
  - Register 258 saves pushed buttons until readout of register

- Set Point Adjustment
  - Up to two set points can be adjusted
  - When pushing the button, the corresponding set point is indicated in the display
  - Set point 1 can only be used in the mode “room occupied”
- Adjustment of Fan Stages
  - The corresponding fan stage is automatically shown in the display
- Adjustment of Room Occupancy
  - The corresponding room occupancy is shown automatically in the display

## 2.6 Temperature Calibration Mode

Each temperature sensor is calibrated during production by the manufacturer. Due to the fact, that the temperature measuring with flush-mounting sensors is besides the voltage-dependent self-heating of the electronics also affected by the temperature dynamic of the wall, a recalibration might become necessary in some cases.

For the user the calibration mode offers the possibility to make a supplementary calibration via the operating buttons without needing a service engineer to make these adjustments via the RS485 bus. Also changeable is the basic set point, lower set point adjustment and upper set point, night-lowering and jump distance set point change.

**Polling of calibration mode:** Parallel actuation of the buttons **T1 and T4** for a time exceeding 5s.

**Chose parameter:** Button T3 or T4

**Adjust Temperature:** Button T1 for **- 0,1**  
Button T2 for **+ 0,1**

**Exit Calibration Mode:** No button actuation for a time exceeding 10s.

## 2.7 Control

### 2.7.1 Device Types

The control is integrated in the following devices: AO2V, OVR, OVT, DO2R, DO2T, AOV, AOFV.

### 2.7.2 Function Mode of PI-Controller

The integrated PI-controller controls the temperature (register 0x0102) of set point 1 (Register 0x0104). The control variable resulting is directly output to the outputs. The PI-controller can be adjusted by properties. The control variable of the controller is re-calculated approx. every 10 seconds. Thus, changes, such as e.g. adjustment of set point or triggering of window contact are only considered after expiration of the control time.

### 2.7.3 Change-Over-mode AOV, AOFV

The device could work for 4-pipe-systems and also for 2-pipe-systems (Change-over mode). The device types AOV and AOFV work with change-over mode. By using change-over mode with Holding Register „Controller mode“ (Address 0x215) could the mode of the controller be selected. **Change-over mode work on output 2!**

### 2.7.4 Energy Stop / Dew Point Detector

If a window contact or a dew point detector are connected to the digital inputs and the digital inputs are parameterized as the same, both are directly affecting the control.

### 2.7.5 Override of Controller

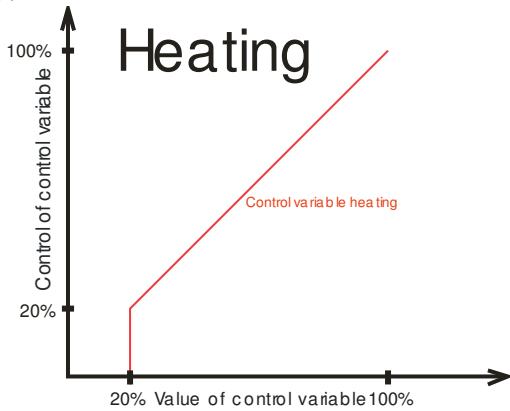
By setting the symbols (window, dew point, off, heating and cooling, input register 0x0101 – 0x0105) of a building control technology, the control can be affected and overwritten directly.

### 2.7.6 Minimal Control Variable

By means of the property “Use minimal control variable with control variable = 0“ (Coil-Bit 28 = 0) the minimal control variable is only used, if the control variable is > 0. If Coil-Bit 28 is =1, the minimal control variable is also used if the control variable is = 0.

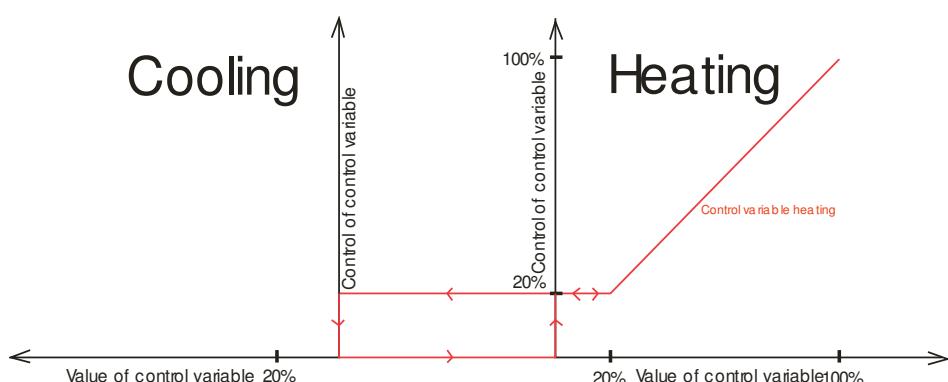
Chose mode control variable (**Register 0x001B**)

- (1) Chose mode control variable = 1  
 $Y_{min} = 20\%$



The control variable is only sent to the output if the calculated value of the control variable is bigger than the minimal control variable.

- (2) Chose mode control variable = 0  
 $Y_{min} = 20\%$



The minimal control variable at the output remains unchanged until the controller changes the operating mode

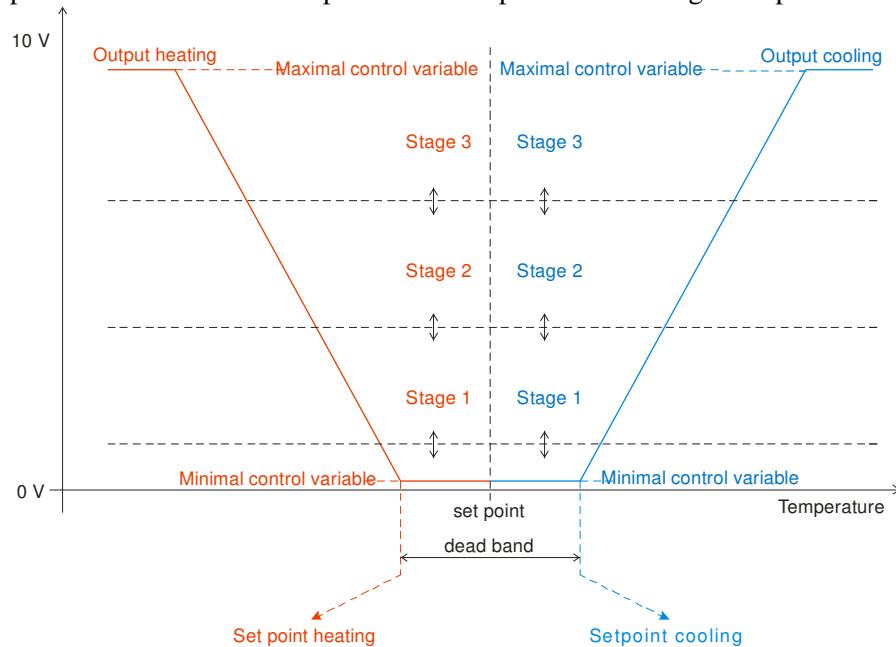
### 2.7.7 Display of set point

The controller uses set point 1 as control set point (Register 0x0104). After reset the controller uses the set point which was set in register 44. There are 2 possibilities for displaying the set point:

- Basic set point + adjustment
  - Heating mode: Set point = Basic set point + manual adjustment
  - Cooling mode: Set point = Basic set point + manual adjustment
- Real control variable – set point is shown which is used by the controller
  - Heating mode: Set point = Basic set point – dead band / 2 + manual adjustment
  - Cooling mode: Set point = Basic set point + dead band / 2 + manual adjustment

### 2.7.8 Fan speed AOFV

The device type AOFV can control a fan with 0-10 V and could control a valve. The fan stages are parameterizable. The output of the fan speed is on analogue output 1.



### 2.7.9 Manual mode / automatic mode

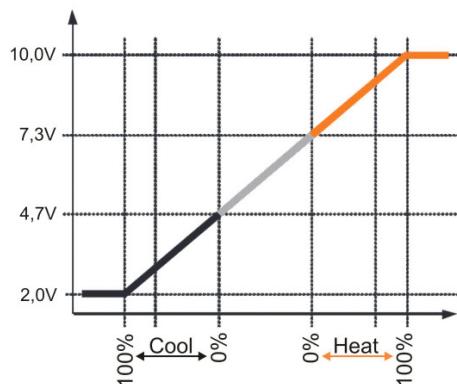
The analogue outputs could be set from a DDC via register 0x0216 and 0x0217. To remove the manual mode set register 0x0216 respectively 0x0217 to -1 / 0xFFFF.

### 2.7.10 Type 6WV for BELIMO 6-Way Valve

The device type 6WV can control Belimo 6-way valves. The control variable is calculated by the integrated PI controller of the WRF06.

100...0% cooling  $\Rightarrow$  2,0...4,7V

0...100% heating  $\Rightarrow$  7,3...10,0V



## 2.8 Hardware Installation

The room operating panel can be connected by means of a twisted-pair cable (line resistance 120 Ohm). For detailed information on installation and mounting, please see the product data sheet WRF06-RS485-Modbus and the data sheet wiring\_rs485\_network.pdf.

## 2.9 RS485 Transceiver

The maximum number of bus participants without use of a repeater is preset by the RS485-transceiver. The transceiver used enables 32 devices per bus segment at maximum.

## 2.10 Protocol

The room operating panel WRF06-RS485-Modbus is a slave-bus participant only allowed to send to the bus on demand of the master. The protocol corresponds to the defaults of:

- MODBUS Application Protocol Specification V1.1
- MODBUS via Serial Line Specification & Implementation guide V1.0

## 2.11 Configuration Options

By means of the DIP switch the device can be adapted to the corresponding bus topology.

5pole DIP switch:

- Bus address of device (1 - 31) via 5 pole DIP switch; DIP switch: 1-5 = 6pole DIP switch:
- Transmitting mode
  - DIP 1 off: RTU
  - DIP 1 on: ASCII
- Baud rate
  - DIP 2 off + DIP 3 off: 9600
  - DIP 2 on + DIP 3 off: 19200
  - DIP 2 off + DIP 3 on: 57600
- Parity
  - DIP 4 off + DIP 5 off: non
  - DIP 4 on + DIP 5 off: even
  - DIP 4 off + DIP 5 on: uneven
- Bus terminating resistor 120 Ohm
  - DIP 6 off
  - DIP 6 on
- The number of data bits is fixed and preset to: RTU 8 data bits and ASCII 7 data bits

As the data sheet contains a detailed description of position and meaning of the jumpers, please refer to the file „Produktblatt\_wrf06\_rs485.pdf“.

**Important notice for operation in the Master/Slave-System:**

**!! The bus address must be adjusted differently for each device**

**!! Transmission mode, baud rate and parity must be identical**

### 3 WRF06-RS485-Modbus Protocol

#### 3.1 Control Commands Supported

The following MODBUS – control commands are supported:

Description	Function Code	
Read bits	01 (hex)	1 (dez)
	02 (hex)	2 (dez)
Read register	03 (hex)	3 (dez)
	04 (hex)	4 (dez)
Write individual bit	05 (hex)	5 (dez)
Write individual register	06 (hex)	6 (dez)
Write several bits	0F (hex)	15 (dez)
Write several registers	10 (hex)	16 (dez)

Table 1

#### 3.2 Data Administration

All data in a MODBUS-Slave are allocated to addresses. Data access (read or write) is made by the corresponding control command and the indication of the corresponding data address.

#### 3.3 EEprom – non volatile memory

Configuration parameters are not allowed to write permanently. Device has maximum write cycles of nonvolatile memory. (dimension: <10000).

### 3.4 Register Definition

#### 3.4.1 Configuration Register

Register	Data Address	Value Range	Description
<b>1 R</b>	<b>0x0000</b>	<b>0x0200</b>	<b>Device coding, not changeable</b>
<b>2 R</b>	<b>0x0001</b>	<b>0x0012</b>	<b>Firmware version, not changeable</b>
<b>2 – 52</b>	<b>0x0002 – 0x0033</b>		<b>Configuration of the operating panel, EEPROM- data – !! Don't update permanently EEprom !!</b>
3 R/W	0x0002	0x0000	Type 2V (AO1: Temperature, AO2: set point)
		0x0001	Type 4DI (4 digital Inputs)
		0x0002	Type AO2V (AO1: Heating, AO2: cooling)
		0x0003	Type DO2R (DO1: Heating, AO2: cooling)
		0x0004	Type DO2T (DO1: Heating, AO2: cooling)
		0x0005	Type OVR (DO1: Heating, AO2: cooling)
		0x0006	Type OVT (DO1: Heating, AO2: cooling)
		0x0007	Type 2VPS (AO1: occupancy, AO2: set point)
		0x0008	Type AOV (AO2: Heating / cooling)
		0x0009	Type AOFV (AO1: Fan speed, AO2: Heating / cooling)
		0x000A	Type VSS (AO1: set point 2, AO2: set point 1)
		0x000B	Type VNS (AO1: temperature, AO2: set point night temp)
		0x000C	Type AOK (AO1: Heating, AO2: cooling)
		0x00D	Type 6WV (AO1: Fan speed, AO2: Heating / cooling)
4 R/W	0x0003	0x0000-0xFFFF	Device location identification (default = 0x0000)
5 R/W	0x0004	0x0000-0x00FF	Intensity background illumination LCD, after 15s without button actuation (rest) (default = 0x000A)
6 R/W	0x0005	0x0000-0x00FF	Intensity background illumination LCD with button actuation (active) (default = 0x00D0)
7 R/W	0x0006	0x0000-0x00FF	Function button -T1
8 R/W	0x0007	0x0000-0x00FF	Function button -T2
9 R/W	0x0008	0x0000-0x0013	Function button -T3

Register	Data Address	Value Range	Description	
10 R/W	0x0009	0x0000-0x0013	Function button -T4	0x31, Control Heating 0x32, Control Cooling 0x33, Control Automatic 0x34, Control Off 0x35, Control Heat / Cool – toggle
11 R/W	0x000A	0x00	Fade out display weekday	
		0x01	Display weekday in English	
		0x02	Display weekday in German	(default)
12 R/W	0x000B	0x00	Fade out display date	
		0x01	Display date in English (JJ.MM.TT)	
		0x02	Display date in German (TT.MM.JJ)	(default)
13 R/W	0x000C	0x00	Fade out display time	
		0x01	Display time	(default)
14 R/W	0x000D	0x00	Display time 24-hours-mode	(default)
		0x01	Display time 12-hours-mode	
15 R/W	0x000E	0x0000-0xFFFF	Updating interval of display in seconds	(default = 0x0A)
16 R/W	0x000F	0x0000-0x0C80	Min-Response-Time	signed int, (max 3100 ms) (default = 0x0A = 10 ms)
17 R/W	0x0010	0x0000-0x00FF	Temperature-Offset for calibration of temperature sensor signed char, e.g. 10 <sub>dez</sub> = +1.0 K, -5 <sub>dez</sub> = -0.5 K	(default = 0x00)
18 R/W	0x0011	0x0000-0xFFFF	Upper adjustable range set temperature 1 signed char, e.g. 30 <sub>dez</sub> = + 3.0 K	(default = 0x001E)
19 R/W	0x0012	0x0000-0xFFFF	Lower adjustable range set temperature 1 signed char, e.g. 30 <sub>dez</sub> = - 3.0 K	(default = 0xFFE2)
20 R/W	0x0013	0x0000-0x00FF	Jumping distance with set temperature 1 signed char, e.g. 5 <sub>dez</sub> = +/- 0.5 K per button actuation	(default = 0x05)
21 R/W	0x0014	0x0000-0xFFFF	Set temperature 1 – Basic set point after reset	Set temperature 1 – Basic set point after reset
22 R/W	0x0015	0x0000-0xFFFF	Upper adjustable range set temperature 2 signed char, e.g. 30 <sub>dez</sub> = + 3.0 K	(default = 0x001E)
23 R/W	0x0016	0x0000-0xFFFF	Lower adjustable range set temperature 2 signed char, e.g. 30 <sub>dez</sub> = - 3.0 K	(default = 0xFFE2)
24 R/W	0x0017	0x0000-0xFFFF	Jumping distance with set temperature 2 signed char, e.g. 5 <sub>dez</sub> = +/- 0.5 K per button actuation	(default = 0x05)
25 R/W	0x0018	0x0000-0xFFFF	Set temperature 2 – Basic set point after reset	Set temperature 2 – Basic set point after reset
26 R/W	0x0019	0x0000-0x0003	Number of fan stages	(default = 0x03)
27 R/W	0x001A	0x0000-0x0003	Selection digital input 1	0x00, none function 0x01, Open contact 0x02, Open dew point 0x03, Open energy hold off 0x04, Open alarm message 0x05, Open room occupancy 0x06, Open message 0x07, Open controller auto / Off 0x08, Open ctrl Heating / Cooling 0x09, Open counter rising edge 0x0A, Open count rising/falling edge 0x0B, Open impulse time
28 R/W	0x001B	0x0000-0x0003	Selection digital input 2	

Register	Data Address	Value Range	Description	
29 R/W	0x001C	0x0000-0x0003	Selection digital input 3 Only device DI4	0x0C, Open Reset set temperature 1 0x10, Close contact 0x11, Close dew point 0x12, Close energy hold off 0x13, Close message 0x14, Close room occupancy 0x15, Close message 0x16, Close Controller auto / Off 0x17, Close Ctrl Heating / Cooling 0x18, Close counter rising edge 0x19, Close count rising/falling edge 0x1A, Close impulse time 0x1B, Close Reset set temperature 1
30 R/W	0x001D	0x0000-0x0003	Selection digital input 4 Only device DI4	
31 R/W	0x001E	0x0000-0x0064	Proportional range Xp (K) Heating Xp = 0 deactivates controller	(default = 0x28 ) e.g. 40 <sub>dez</sub> = 4.0 K
32 R/W	0x001F	0x0000-0x00FF	Reset time Tn (min) Heating	(default = 0x64) e.g. 100 <sub>dez</sub> = 100 min
33 R/W	0x0020	0x0000-0x0064	Proportional range Xp (K) Cooling Xp = 0 deactivates controller	(default = 0x28 ) e.g. 40 <sub>dez</sub> = 4.0 K
34 R/W	0x0021	0x0000-0x00FF	Reset time Tn (min) Cooling	(default = 0x64) e.g. 100 <sub>dez</sub> = 100 min
35 R/W	0x0022	0x0000-0x0064	Night-lowering (unoccupied) Heating = Set point 1 – night lowering Cooling = Sollwert1 + night lowering	(default = 0x28) e.g. 40 <sub>dez</sub> = 4.0 K
36 R/W		0x0000-0x0064	Dead zone between heating and cooling	(default = 0x28) e.g. 40 <sub>dez</sub> = 4.0 K
37 R/W	0x0024	0x0000-0x0064	Antifreeze 0x00 deactivates antifreeze	(default = 0x3C) e.g. 60 <sub>dez</sub> = 6.0 K
38 R/W	0x0025	0x0000-0x0064	Maximal control variable limit Heating	(default = 0x64) e.g. 100 <sub>dez</sub> = 100 %
39 R/W	0x0026	0x0000-0x0064	Minimal control variable limit Heating	(default = 0x00) e.g. 100 <sub>dez</sub> = 0 %
40 R/W	0x0027	0x0000-0x0064	Maximal control variable limit Cooling	(default = 0x64) e.g. 100 <sub>dez</sub> = 100 %
41 R/W	0x0028	0x0000-0x0064	Minimal control variable limit Cooling	(default = 0x00) e.g. 100 <sub>dez</sub> = 0 %
42 R/W	0x0029	0x0000-0x00FF	PWM-Cycle time	(default = 0x0F) e.g. 15 <sub>dez</sub> = 15 min
43 R/W	0x002A	0x0000-0x00FF	Set back room occupancy to night	(default = 0x00) e.g. 120 <sub>dez</sub> = 120 min
44 R/W	0x002B	0x0000-0x0003	Controller mode	(default = 0x03) 0 – Controller off 1 – Controller heating 2 – Controller cooling 3 – Controller automatic
45 R/W	0x002C	0x0000-0x0064	Fan speed 1 heating	(default = 0x0A) e.g. 10 <sub>dez</sub> = 1 V
46 R/W	0x002D	0x0000-0x0064	Fan speed 2 heating	(default = 0x1E) e.g. 30 <sub>dez</sub> = 3 V

<b>Register</b>	<b>Data Address</b>	<b>Value Range</b>	<b>Description</b>	
47 R/W	0x002E	0x0000-0x0064	Fan speed 3 heating	(default = 0x46) e.g. 70 <sub>dez</sub> = 7 V
48 R/W	0x002F	0x0000-0x0064	Fan speed 1 cooling	(default = 0x0A) e.g. 10 <sub>dez</sub> = 1 V
49 R/W	0x0030	0x0000-0x0064	Fan speed 2 cooling	(default = 0x1E) e.g. 30 <sub>dez</sub> = 3 V
50 R/W	0x0031	0x0000-0x0064	Fan speed 3 cooling	(default = 0x46) e.g. 70 <sub>dez</sub> = 7 V
51 R/W	0x0032	0x0000-0x0003	Minimal fan speed heating	(default = 0x00) e.g. 1 <sub>dez</sub> = Fan speed 1
52 R/W	0x0033	0x0000-0x0003	Minimal fan speed cooling	(default = 0x00) e.g. 1 <sub>dez</sub> = Fan speed 1

### 3.4.2 Output Register

Register	Data Address	Value Range	Description			
257 – 269 R	0x0100 – 0x010C	Measuring value (data output)				
257 R	0x0100	0x0000-0x000F	bit0	button 1	1=pressed,	0=not pressed
			bit1	button 2	1=pressed,	0=not pressed
			bit2	button 3	1=pressed,	0=not pressed
			bit3	button 4	1=pressed,	0=not pressed
258 R	0x0101	0x0000-0x000F	It is buffered if a button was actuated since the last read out of the register. After the read out, all bits are reset to the actual value.			
			bit0	button 1	1=pressed,	0=not pressed
			bit1	button 2	1=pressed,	0=not pressed
			bit2	button 3	1=pressed,	0=not pressed
			bit3	button 4	1=pressed,	0=not pressed
259 R	0x0102	0x0000-0xFFFF	Temperature		signed int, e.g. 184 <sub>dez</sub> = 18.4 °C	
260 R	0x0103	0x0000-0xFFFF	Set temperature 1 offset		signed char, e.g. -25 <sub>dez</sub> = -2.5K	
261 R	0x0104	0x0000-0xFFFF	Set temperature 1 effective		signed int, e.g. 220 <sub>dez</sub> = 22.0 °C Sum 0x26/0x27 + 0x104	
262 R	0x0105	0x0000-0xFFFF	Set temperature 2 offset		signed char, e.g. -25 <sub>dez</sub> = -2.5K	
263 R	0x0106	0x0000-0xFFFF	Set temperature 2 effective		signed int, e.g. 220 <sub>dez</sub> = 22.0 °C Sum 0x26/0x27 + 0x104	
264 R	0x0107	0x0000-0x0003 0xFF00-0xFF03	Fan stage		0 – Off 1 – Stage 1 2 – Stage 2 3 – Stage 3 0xFF00 – Auto Off 0xFF01 – Auto Stage 1 0xFF02 – Auto Stage 2 0xFF03 – Auto Stage 3	
265 R	0x0108	0x0000-0x0001	Room occupancy		0 – Room unoccupied 1 – Room occupied	
266 R	0x0109	0x0000-0x0001	Digital input 1		0 – opened 1 – closed	
267 R	0x010A	0x0000-0x0001	Digital input 2		0 – opened 1 – closed	

Register	Data Address	Value Range	Description
<b>257 – 270 R</b>	<b>0x0100 – 0x010D</b>		<b>Measuring value (data output)</b>
268 R	0x010B	0x0000-0x03FF	2V: Temperature unsigned int e.g. 409 = 20.0°C = 4V
		0x0000-0x0001	DI4: Digital input 3 0 – opened 1 – closed
		0x0000-0x03FF	AO2V, DO2R,DO2T, OVR, OVT: Control variables unsigned int e.g. 511 = 50%
		0x0000-0x03FF	AOV, AOFV: Control variable Heating / Cooling unsigned int e.g. 511 = 50%
		0x0000-0x03FF	6WV: Control voltage for 6-way valve 0...1023dec = 0...10V
269 R	0x010C	0x0000-0x03FF	2V: Set point unsigned int e.g. 450 = 22.0°C = 4.4V
		0x0000-0x0001	DI4: Digital input 4 0 – opened 1 – closed
		0x0000-0x03FF	AO2V, DO2R,DO2T, OVR, OVT: Control variable cooling unsigned int e.g. 614 = 60%
		0x0000-0x03FF	AOFV, 6WV: Fan speed 0...1023dec = 0...10V
270 R	0x010D	0x0000-0x0004	Controller mode 0 – Controller off 1 – Controller heating 2 – Controller cooling 3 – Controller automatic heating 4 – Controller automatic cooling

### 3.4.3 Input register

Register	Data Address	Value Range	Description
513 - 536	0x0200 - 0x0217		Control (ext. data default)
Register 0x0200 – 0x0205: Updating of time			
If the registers are written, weekday, date and time are indicated in the display. The display format is defined by the configuration registers 0x001D – 0x0020.			
513 R/W	0x0200	0x0000-0x003B	Seconds 0 – 59 B7 B6 B5 B4 B3 B2 B1 B0 seconds
514 R/W	0x0201	0x0000-0x003B	Minutes 0-60 B7 B6 B5 B4 B3 B2 B1 B0 minutes
515 R/W	0x0202	0x0000-0x0017	Hours 0 - 23h B7 B6 B5 B4 B3 B2 B1 B0 hours
516 R/W	0x0203	0x0000-0x001F	Day 1-31 B7 B6 B5 B4 B3 B2 B1 B0 day
517 R/W	0x0204	0x0000-0x000C	Month 1-12 B7 B6 B5 B4 B3 B2 B1 B0 month
518 R/W	0x0205	0x0000-0x0833	Year 2000-2099 B7 B6 B5 B4 B3 B2 B1 B0 year
519 R/W	0x0206		reserve
520 R/W	0x0207	0x0000-0xFFFF	External value 1 signed int, e.g. 234 <sub>dez</sub> = 23.4°C fade in with Coil 0x0001
521 R/W	0x0208	0x0000-0xFFFF	External value 2 signed int, e.g. 234 <sub>dez</sub> = 23.4°C fade in with Coil 0x0002
522 R/W	0x0209	0x0000-0xFFFF	External value 3 signed int, e.g. 234 <sub>dez</sub> = 23.4°C fade in with Coil 0x0003
523 R/W	0x020A	0x0000-0xFFFF	External value 4 signed int, e.g. 234 <sub>dez</sub> = 23.4°C fade in with Coil 0x0004
524 R/W	0x020B	0x0000-0xFFFF	Set point 1 offset signed char, e.g. -25 <sub>dez</sub> = -2.5K fade in with Coil 0x0005
525 R/W	0x020C	0x0000-0xFFFF	Set point 2 offset signed char, e.g. -25 <sub>dez</sub> = -2.5K fade in with Coil 0x0007
526 R/W	0x020D	0x0000-0xFFFF	Basic set point 1 signed char, e.g. 220 <sub>dez</sub> = 22 °C
527 R/W	0x020E	0x0000-0xFFFF	Basic set point 2 signed char, e.g. 220 <sub>dez</sub> = 22 °C

Register	Data Address	Value Range	Description	
528 R/W	0x020F	0x0000-0xFFFF	Fan stage	signed int, 0 <sub>dez</sub> = Off 1 <sub>dez</sub> = Stage 1 2 <sub>dez</sub> = Stage 2 3 <sub>dez</sub> = Stage 3 signed int, 0xFF00 = Auto Off 0xFF01 = Auto Stage 1 0xFF02 = Auto Stage 2 0xFF03 = Auto Stage 3
529 R/W	0x0210	0x0000-0x0001	Room occupancy	0 – Room unoccupied 1 – Room occupied
530 R/W	0x0211	0x0000-0x0001	Alarm message 1	0 – fade out 1 – fade in
531 R/W	0x0212	0x0000-0x0001	Alarm message 2	0 – fade out 1 – fade in
532 R/W	0x0213	0x0000-0x0001	Alarm message 3	0 – fade out 1 – fade in
533 R/W	0x0214	0x0000-0x0001	Alarm message 4	0 – fade out 1 – fade in
534 R/W	0x0215	0x0000-0x0003	Controller mode	0 – Controller off 1 – Controller heating 2 – Controller cooling 3 – Controller automatic heating
535 R/W	0x0216	0xFFFF -0x03FF	Manual set analogue output 2	signed int, e.g. 512 <sub>dez</sub> = 50 % = 5 V automatic= 0xFFFF / -1
536 R/W	0x0217	0xFFFF -0x03FF	Manual set analogue output 1	signed int, e.g. 512 <sub>dez</sub> = 50 % = 5 V automatic= 0xFFFF / -1
537 R/W	0x0218	0x0000-0xFFFF	Temperature (external)	signed char, e.g. 220 <sub>dez</sub> = 22 °C internal Temp.: 0x7FFF/32767

Data-Address	Description
0xFF00 – 0xFFFF	Range defined by the manufacturer, not allowed to be changed!

### 3.4.4 Text Row Line 1 and Line 2

Register	Data Address	Value Range	Description									
<b>769 – 988 R/W</b>	<b>0x0300 – 0x03DD</b>		<b>Configuration Property – !! Don't update permanently EEeprom !!</b>									

BS 1-14 = ASCII letter

Example for row 1: Set point 1

R 769		R 770		R 771		R 772		R 773		R 774		R 775	
Hi	Lo												
S	o	L	1	w	e	r	t		1				
0x53	0x6F	0x6C	0x6C	0x77	0x65	0x72	0x74	0x20	0x31	0x20	0x20	0x20	0x20

Example for row 2: Room 1

R 779		R 780		R 781		R 782		R 783		R 784		R 785	
Hi	Lo												
R	a	u	m		1								
0x52	0x61	0x75	0x6D	0x20	0x31	0x20	0x20	0x20	0x20	0x20	0x20	0x20	0x20

- Input of letters and numbers in ASCII format
- If no input is made, row 1 and row 2 are not changed in the display
- If there is no sign in row 2 (0x00), row 1 is displayed in type size 2 (7 signs)
- If row 1 and row 2 are written, up to 14 signs can be displayed in type size 1.

769 R/W -778	0x0300	0x0000- 0xFFFF	Set Point 1 Row 1	Register 769	Register 770	...	Register 775
				High	Low	High	Low
779 R/W -788	0x030A	0x0000- 0xFFFF	Set Point 1 Row 2	BS 1	BS 2	BS 3	BS 4
				High	Low	High	Low
789 R/W -798	0x0314	0x0000- 0xFFFF	Set Point 2 Row 1	BS 1	BS 2	BS 3	BS 4
				High	Low	High	Low
799 R/W -808	0x031E	0x0000- 0xFFFF	Set Point 2 Row 2	BS 1	BS 2	BS 3	BS 4
				High	Low	High	Low
809 R/W -818	0x0328	0x0000- 0xFFFF	External Measuring Value 1 Row 1	BS 1	BS 2	BS 3	BS 4
				High	Low	High	Low
819 R/W -828	0x0332	0x0000- 0xFFFF	External Measuring value 1 Row 2	BS 1	BS 2	BS 3	BS 4
				High	Low	High	Low

829 R/W -838	0x033C	0x0000- 0xFFFF	External Measuring value 2 Row 1	Register 829	Register 830	...	Register 835
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
839 R/W -848	0x0346	0x0000- 0xFFFF	External Measuring Value 2 Row 2	Register 839	Register 840	...	Register 845
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
849 R/W -858	0x0350	0x0000- 0xFFFF	External Measuring Value 3 Row 1	Register 849	Register 850	...	Register 855
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
859 R/W -868	0x035A	0x0000- 0xFFFF	External Measuring Value 3 Row 2	Register 859	Register 860	...	Register 865
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
869 R/W -878	0x0364	0x0000- 0xFFFF	External Measuring Value 4 Row 1	Register 869	Register 870	...	Register 875
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
879 R/W -888	0x036E	0x0000- 0xFFFF	External Measuring Value 4 Row 2	Register 879	Register 880	...	Register 885
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
889 R/W -898	0x0378	0x0000- 0xFFFF	Alarm Message 1 Row 1	Register 889	Register 890	...	Register 895
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
899 R/W -908	0x0382	0x0000- 0xFFFF	Alarm Message 1 Row 2	Register 899	Register 900	...	Register 905
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
909 R/W -918	0x038C	0x0000- 0xFFFF	Alarm Message 2 Row 1	Register 909	Register 910	...	Register 915
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
919 R/W -928	0x0396	0x0000- 0xFFFF	Alarm Message 2 Row 2	Register 919	Register 920	...	Register 925
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4
929 R/W -938	0x03A0	0x0000- 0xFFFF	Alarm Message 3 Row 1	Register 929	Register 930	...	Register 935
				High	Low	High	Low
				BS 1	BS 2	BS 3	BS 4

939 R/W -948	0x03AA	0x0000- 0xFFFF	Alarm Message 3 Row 2	Register939		Register 940		...		Register 945	
				High	Low	High	Low			High	Low
				BS 1	BS 2	BS 3	BS 4			BS 13	BS 14
949 R/W -958	0x03B4	0x0000- 0xFFFF	Alarm Message 4 Row 1	Register 949		Register 950		...		Register 955	
				High	Low	High	Low			High	Low
				BS 1	BS 2	BS 3	BS 4			BS 13	BS 14
959 R/W -968	0x03BE	0x0000- 0xFFFF	Alarm Message 4 Row 2	Register 959		Register 960		...		Register 965	
				High	Low	High	Low			High	Low
				BS 1	BS 2	BS 3	BS 4			BS 13	BS 14
969 R/W -978	0x03C8	0x0000- 0xFFFF	Room temperature Row 1	Register 969		Register 970		...		Register 975	
				High	Low	High	Low			High	Low
				BS 1	BS 2	BS 3	BS 4			BS 13	BS 14
979 R/W -988	0x03D2	0x0000- 0xFFFF	Room temperature Row 2	Register979		Register 980		...		Register 985	
				High	Low	High	Low			High	Low
				BS 1	BS 2	BS 3	BS 4			BS 13	BS 14

### 3.4.5 Unit Row 1, Row 2 and Row 3

Register	Data Address	Value Range	Description											
<b>1024– 1083 R/W</b>	<b>0x0400 – 0x043B</b>	<b>Configuration Properties – !! Don't update permanently EEeprom !!</b>												

BS 1-3 = ASCII letter  
 Example for row 1, row 2: °C and row 3: out

R 1044	R 1045	R 1046	1047		R 1048		R 1049		R 1050		
Hi	Lo	Hi	Lo	Hi	Lo	Hi	Lo	Hi	Lo	Hi	Lo
°	C					O	u	t			
0xB0	0x43	0x00	0x00	0x00	0x00	0x4F	0x75	0x74	0x00	0x00	0x00

- Input of letters and numbers in ASCII format
- If no input is made, row 1, row 2 and row 3 are not changed in the display
- If there is no sign in row 2 (0x00), row 1 is displayed in type size 2 (1 sign)
- If row 1 and row 2 are written, up to 3 signs per line can be displayed in type size 1
- Row 3 is displayed in type size 1 (3 signs)

1024 R/W -1033	0x0400	0x0000- 0xFFFF	Unit Set Point 1	Reg 1024	Reg 1025	...	Reg 1029
				High	Low	High	Low
				BS 1	BS 2	BS 3	0x00
1034 R/W -1043	0x040A	0x0000- 0xFFFF	Unit Set Point 2	Reg 1034	Reg 1035	...	Reg 1039
				High	Low	High	Low
				BS 1	BS 2	BS 3	0x00
1044 R/W -1053	0x0400	0x0000- 0xFFFF	Unit External Measuring Value 1	Reg 1044	Reg 1045	...	Reg 1049
				High	Low	High	Low
				BS 1	BS 2	BS 3	0x00
1054 R/W -1053	0x0400	0x0000- 0xFFFF	Unit External Measuring Value 2	Reg 1054	Reg 1055	...	Reg 1059
				High	Low	High	Low
				BS 1	BS 2	BS 3	0x00
1064 R/W -1063	0x0400	0x0000- 0xFFFF	Unit External Measuring Value 3	Reg 1064	Reg 1065	...	Reg 1069
				High	Low	High	Low
				BS 1	BS 2	BS 3	0x00
1074 R/W -1083	0x0400	0x0000- 0xFFFF	Unit External Measuring Value 4	Reg 1074	Reg 1075	...	Reg 1079
				High	Low	High	Low
				BS 1	BS 2	BS 3	0x00

### 3.5 Bit Allocation / Coil Definition

#### 3.5.1 Configuration Bits

Bit	Data Address	Description	
<b>0x0000 – 0x0020</b>		<b>Configuration of Operating Panel Bit-Register, EEPROM- Data</b> <b>Configuration of Display Field 2 –</b> <b>!! Don't update permanently EEprom !!</b>	
1 R/W	0x0000	Room temperature	1 = display 0 = do not display
2 R/W	0x0001	External value default 1 Value of 0x0207	1 = display 0 = do not display
3 R/W	0x0002	External value default 2 Value of 0x0208	1 = display 0 = do not display
4 R/W	0x0003	External value default 3 Value of 0x0209	1 = display 0 = do not display
5 R/W	0x0004	External value default 4 Value of 0x020A	1 = display 0 = do not display
6 R/W	0x0005	Set Point 1 offset Value of 0x0103	1 = display 0 = do not display
7 R/W	0x0006	Set Point 1 effective Value of 0x0104	1 = display 0 = do not display
8 R/W	0x0007	Set Point 2 offset Value of 0x0105	1 = display 0 = do not display
9 R/W	0x0008	Set Point 2 effective Value of 0x0106	1 = display 0 = do not display
10 R/W	0x0009	Time	1 = display 0 = do not display
11 R/W	0x000A	Date 1 = display	0 = do not display
12 R/W	0x000B	Room Occupancy	1 = display 0 = do not display
13 R/W	0x000C	Fan Stage	1 = display 0 = do not display
14 R/W	0x000D	Reserved	
15 R/W	0x000E	Reserved	
16 R/W	0x000F	Reserved	
17 R/W	0x0010	Display Temperature	1 = with tenth digit 0 = without tenth digit
18 R/W	0x0011	Display External Value 1	1 = with tenth digit 0 = without tenth digit
19 R/W	0x0012	Display External Value 2	1 = with tenth digit 0 = without tenth digit
20 R/W	0x0013	Display External Value 3	1 = with tenth digit 0 = without tenth digit

Bit	Data Address	Description	
<b>0x0000 – 0x0020</b>		<b>Configuration of Operating Panel Bit-Register, EEPROM- Data – !! Don't update permanently EEprom !!</b>	
21 R/W	0x0014	Display External Value 4	1 = with tenth digit 0 = without tenth digit
22 R/W	0x0015	Display Set Point 1	1 = with tenth digit 0 = without tenth digit
23 R/W	0x0016	Display Set Point 2	1 = with tenth digit 0 = without tenth digit
24 R/W	0x0017	Display Set Point 1	1 = Basic set point + Offset 0 = Controls et point
25 R/W	0x0018	°C/°F	1 = °C 0 = °F
26 R/W	0x0019	Display Adjustment Set Point 1	1 = Set point effective 0 = Set point offset
27 R/W	0x001A	Display Adjustment Set Point 2	1 = Set point effective 0 = Set point offset
28 R/W	0x001B	Use Minimal Control Variable with control variable > 0: = 1 Use Minimal Control Variable with control variable = 0: = 0	
29 R/W	0x001C	Room occupancy after voltage reset	1 = Room occupied 0 = Room unoccupied
30 R/W	0x001D	Activate device by 1. Button press	1 = activ 0 = not activ
31 R/W	0x001E	Save actual room occupancy	1 = Save 0 = Don't save
32 R/W	0x001F	Reserved	

### 3.5.2 Input Bits

<b>Bit</b>	<b>Data Address</b>	<b>Description</b>
<b>0x0100 – 0x010F</b>		<b>Input Value of Operating Panel Bit-Register Override of Controller</b>
257 R/W	0x0100	Symbol Failure                  1 = ON, 0 = OFF
258 R/W	0x 0101	Symbol Heating - Controller Heating Mode      1 = ON, 0 = OFF
259 R/W	0x0 102	Symbol Cooling - Controller Cooling Mode      1 = ON, 0 = OFF
260 R/W	0x0 103	Symbol Window - Energy Stop      1 = ON, 0 = OFF
261 R/W	0x0 104	Symbol Dew Point - Dew Point Alarm      1 = ON, 0 = OFF
262 R/W	0x 0105	Symbol Off - Controller off      1 = ON, 0 = OFF
263 R/W	0x 0106	Without Function
264 R/W	0x 0107	Without Function
265 R/W	0x 0108	Without Function
266 R/W	0x 0109	Without Function
267 R/W	0x0 10A	Without Function
268 R/W	0x0 10B	Without Function
269 R/W	0x0 10C	Without Function
270R/W	0x 010D	Without Function
271 R/W	0x 010E	Without Function
272 R/W	0x 010F	Without Function

## 4 Data Transmission

### 4.1 Master/Slave Protocol

One master and one or more slaves are connected to the serial bus. The communication between master and slave is exclusively controlled by the master. The slaves are only allowed to send if they have been addressed by the master before. Slaves are only sending back to the master, never to another slave.

### 4.2 Data Frame

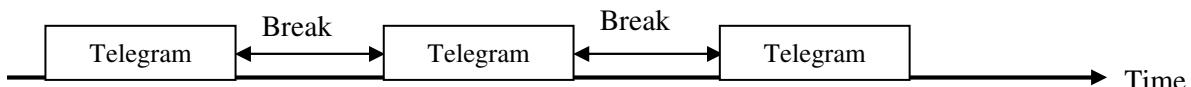
The data are sent to the bus in accordance to severely defined defaults:

Address	Control Command	Data	Checksum
---------	-----------------	------	----------

In general, a MODBUS telegram starts with the address of the slave, followed by a control command (e.g. read register) and the data. By means of the checksum at the telegram end, the bus participants can recognize transmission errors.

### 4.3 Transmission Mode RTU

In the transmission mode RTU telegrams are separated by means of transmission breaks.



The period of the transmission breaks for separating telegrams is depending on the adjusted baud rate and amounts to  $3,5 * \text{word transmission time (11 bit)}$ . With 9600 baud at least 4 ms must pass by and with 57600 at least 1 ms. must pass by between two telegrams.

#### 4.3.1 Telegram Layout

Address 1 Byte	Command Control 1 Byte	Data 0 - 100 byte	Checksum	
			CRC Low	CRC High

#### 4.3.2 Calculation of CRC-Checksum

The CRC checksum (Cyclical Redundancy Check) is calculated by the sender out of all bytes transmitted and is attached to the message.

The receiver re-calculates the CRC checksum and compares it with the checksum received. If the values do not correspond, a transmission error is assumed and the data received are rejected.

The least significant byte of the 16 bit checksum is set to the penultimate location and the most significant byte is set at last location.

Calculation of checksum (Programming example in C):

```

crc = 0xFFFF;                                // CRC-Check, Initialisation
for(i = 0; i < Telegram length-2; i++)
    crc = crc_calc(crc, Telegram data[i]);

crc_low = crc & 0x00FF;                      // Low-Byte
crc_high = (crc & 0xFF00) >> 8;             // High-Byte

// Function definition CRC calculation
unsigned int      crc_calc(unsigned int      crc_temp, unsigned int data)
{
    unsigned int      Index_CC=0;            // Loop counter
    unsigned int      LSB=0;                 // Help variable

    // Exclusive-Orer des 8Bit-Char with the lower 8Bit of CRC
    crc_temp = ( ( crc_temp ^ data) | 0xFF00) & (crc_temp | 0x00FF) ;

    for(Index_CC = 0; Index_CC<8; Index_CC++)
    {
        LSB = (crc_temp & 0x0001);
        crc_temp      >>= 1;
        if(LSB)
            crc_temp = crc_temp ^ 0xA001;           // calculation polynominal für CRC16
    }

    return(crc_temp);
}

```

## 4.4 Transmission Mode ASCII

The ASCII transmission mode does not make that high demands on the computer speed of the bus participants. The telegrams are not separated by break times, but by ASCII control characters.

### 4.4.1 Telegram Layout

The ASCII control character „;“ always identifies the beginning of a telegram. The ASCII control characters „CR“ and „LF“ identify the end of a telegram. The telegram data are output hexa-decimal in the ASCII format:

e.g.: 197dez (1Byte) = C5hex (1 Byte) = C (1 Byte) 5 (1 Byte) ASCII

As one data byte is displayed by 2 ASCII characters, the number of data bytes to be transmitted is doubled compared with the RTU mode.

Start 1 char	Address 2 char	Control command 2 char	Data 0 - 2 x 100 char	Checksum LRC 2 char	End 2 char
:					<b>CR LF</b>

### 4.4.2 Calculation of LRC-Checksum

The LRC checksum (Longitudinal Redundancy Check) is calculated by the sender out of all bytes transmitted (without „;“, „CR“, „LF“) and pasted in the message of „CR“ and „LF“. The receiver recalculates the LRC checksum and compares it with the checksum received. If the values do not correspond, a transmission error is assumed and the data received are rejected.

The most significant ASCII character of the 8 bit checksum is sent in the telegram before the least significant ASCII character.

Calculation of checksum (programming example in C):

```

lrc = 0;
for(i = 1; i < Telegram length -4; i++)
    lrc = lrc + Telegram data [i];

lrc = 0xFF - lrc;
lrc = lrc + 1;

```

## 5 Examples: Telegrams

### 5.1 Register

The operating unit has different registers for the configuration, for the display of values and for the input values.

#### 5.1.1 Parameterization of Operating Unit

The operating unit can be parameterized by the configuration registers 3-42 and the control commands „Write Register“(10hex or 06hex).

Example: button 1 and button 2 for set point adjustment of temperature 1.

Master - Telegram in Transmission Mode RTU:

Device	command	Start address		Number of Register		Number of Bytes	Data Register 08		Data Register 09		Check Sum	
		H Byte	L Byte	H Byte	L Byte		H Byte	L Byte	H Byte	L Byte	L CRC	H CRC
02	10	00	06	00	02	04	00	01	00	02	CRC	

Slave – Response Telegram in Transmisson Mode RTU:

Device	command	Start address		Number of Register		Check Sum	
		H Byte	L Byte	H Byte	L Byte	L CRC	H CRC
02	10	00	06	00	02	CRC	

If button 1 or 2 is pushed, the set point for temperature is changed.

#### 5.12 Read-Out of Output Register

Button status and values are stored in the output registers. After a reset the basic set points are taken over from the configuration registers for the corresponding set points.

Master - Telegram in Modus RTU		Slave – Response Telegram in Modus RTU		
Description		Value (Hex)		Description
Slave address		02		Slave Address
Command		03		Command
Start address High		01		Number of Bytes
Start address Low		00		Register value High (0100)
Number of Registers High		00		Register value Low (0100) Button 1-4
Number of Registers Low		04		Register value High (0101)
Check sum Low		CRC	Register value Low (0101) Button 1-4	
Check sum High			Register value High (0102) Temperature	
			Register value Low (0102) Temperature	
			Register value High (0103) Set point offset	
			Register value Low (0103) Temperature 1	
			FF	
			E7	

		Check sum Low	CRC
		Check sum High	

### 5.1.2 Setting of Input Registers

By means of the input registers different values can be overwritten in the operating unit.

Example: Setting of time: 14:23:47

Master - Telegram in the transmission mode TU:

Device	Command	Start address		Number of Register		Number of Bytes	Data Register 513		Data Register 514		Data Register 515		Check Sum	
		H Byte	L Byte	H Byte	L Byte		H Byte	L Byte	H Byte	L Byte	L Byte	L Byte	L CRC	H CRC
02	10	02	00	00	03	06	00	47	00	23	00	14	CRC	

Slave – Response Telegram in transmission mode RTU:

Device	Command	Start Address		Number of Register		Check Sum	
		H Byte	L Byte	H Byte	L Byte	L CRC	H CRC
02	10	02	00	00	03	CRC	

Example: Setting of date: 23.01.2008

Master - Telegram in transmission mode RTU:

Device	Command	Start address		Number of Register		Number of Bytes	Data Register 516		Data Register 517		Datea Register 518		Check Sum	
		H Byte	L Byte	H Byte	L Byte		H Byte	L Byte	H Byte	H Byte	L Byte	L Byte	L CRC	H CRC
02	10	02	03	00	03	06	00	23	00	01	00	08	CRC	

Slave – Response Telegram in transmission mode RTU:

Device	Command	Start address		Number of Register		Check Sum	
		H Byte	L Byte	H Byte	L Byte	L CRC	H CRC
02	10	02	03	00	03	CRC	

## 5.2 Coil / Bit Allocation

The operating unit has different configuration bits for the setting of the display value in the display. By means of the input bits different symbols and LEDs of the operating unit can be controlled.

### 5.2.1 Configuration Bits

By means of the control command „Write Bit(s)“ (0Fhex or 05hex) a configuration bit (or more) can be written with the value „1“ or „0“.

Example: Display outdoor temperature

Master - Telegram in transmission mode RTU:

Slave Address	Command	Start address		Number of Bits		Number of Bytes	Data	Check Sum	
		H Byte	L Byte	H Byte	L Byte			H Byte	L CRC
02	0F	00	01	00	01	01	01	CRC	

Slave – Response Telegram in transmission mode RTU:

Slave Address	Command	Start address		Number of Bits		Check Sum	
		H Byte	L Byte	H Byte	L Byte	L CRC	H CRC
02	0F	00	01	00	01	CRC	

### 5.2.2 Read Out of Bits

By means of the control command „Read bits“(01hex or 02hex) one or more bits can be read out.

Example: Read out indicated symbols (Data address = 00000hex 00001hex)

Master - Telegram in mode RTU			Slave –Response telegram in mode RTU		
Description	Value (Hex)		Description	Value (Hex)	
Device	02		Device	02	
Command	01		Command	01	
Start address High	00		Number of Bytes	01	
Start address Low	00		Bit value 0,0,0,0,0,Bit1,Bit0	03	
Number of Bits High	00		Check Sum Low	CRC	
Number of Bits Low	02		Check Sum High		
Check Sum Low	CRC				
Check Sum High					

## 6 Configuration Software

By means of a RS485-interface (e.g. RS232-RS485-level converter e.g. ADAM-4520) it is possible to access to the Modbus by the configuration software. The configuration software is not obligatory necessary for the installation of the WRF06-RS485 Modbus. It is possible to use any programme producing Modbus telegrams which is suitable to set registers.

## 7 Software Installation

For the installation of the configuration software, the setup files „WRF06\_Modbus\_Config\_Setup.exe“ must be started. Please note that you must have administrator rights for the installation. During the installation, please follow the screen instructions.

After a successful operation, the configuration software can be started via the  
“Starting Menu/Programs/Thermokon“

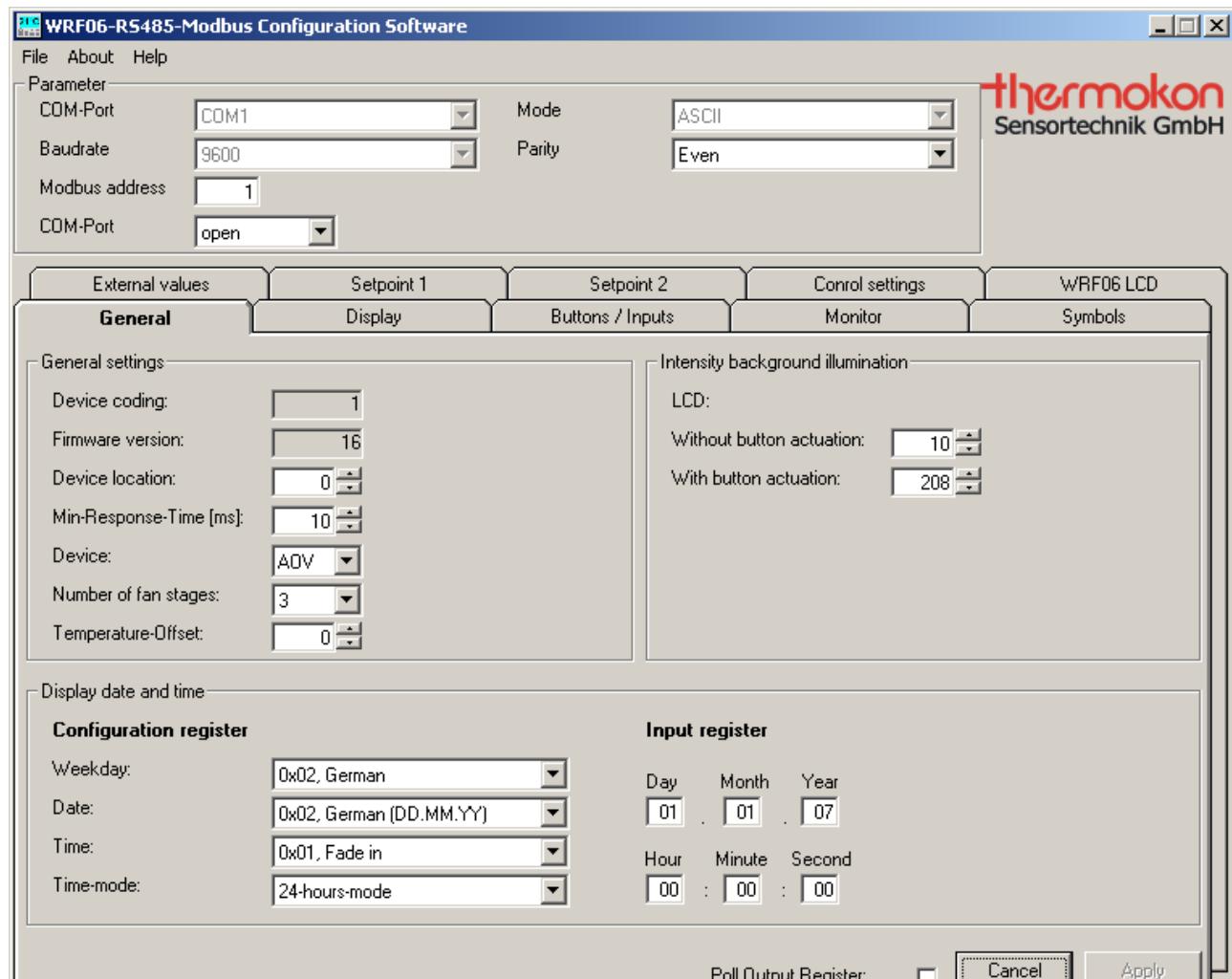
Operating systems supported:      Windows9x;      WindowsNT;      WindowsMe;      Windows2000;  
    WindowsXP; WindowsServer

## 8 Configuration of WRF06-RS485-Modbus

### 8.1 Software Configuration

By means of the configuration software the configuration registers can be clearly adjusted. Output registers of the WRF06 can be read out and input registers can be set. The load of the individual registers is described in chapter 3.4.

Via the menu points "File" and "Saving of Parameter" respectively "Loading of Parameter", the configuration registers can be stored in a text file and can be reloaded into the WRF06-RS485-Modbus.



**Picture 8-1: Configuration Software**

## 8.2 Parameter-Frame

The Modbus can be accessed via the configuration software by means of a COM-Port. In the "Parameter"-Frame hardware settings can be made. They must be in conformity with the Modbus receiver, in order to produce a connection.

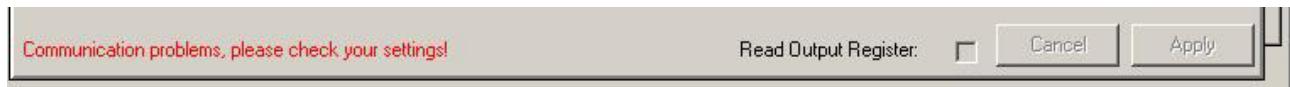
The following options can be selected:

- COM-Port
- Baud rate 9600 , 19200, 57600
- Parity none, even, odd
- Modus for setting of transmission ASCII or RTU
- Modbus address (1-31)

In the field "Modbus address" the address of the WRF06-RS485 Modbus that shall be configured is entered (value between 1 and 31).

Via the selection menu behind "COM-Port" the port can be opened "open" and closed "close".

If the connection failed, the same is shown by an error message.



**Picture 8-2: Communication Problems**

## 8.3 Register

The configuration registers can be set in the different riders. Furthermore, the output registers can be read and the input registers can be set.

Changes are sent to the WRF06-RS485 Modbus after having pressed the button "take over". By actuating the button "Cancel" the registers of the WRF06-RS485-Modbus are read out again.

By activating the hook "read output register" all output registers are read out cyclically.



**Picture 8-3: Data**